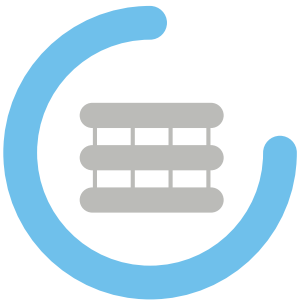


# OpenHPC (v4.2)

## Cluster Building Recipes

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## Rocky 10 Base OS

## Confluent/Slurm Edition for Linux* (aarch64)

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*Document Last Update: 2026-06-05*

*Document Revision: d6b49a4be65ae379e2870143be2c2aae52aed5cd*

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# 1 Introduction

This guide presents a simple cluster installation procedure using components from the OpenHPC software stack. OpenHPC represents an aggregation of a number of common ingredients required to deploy and manage an HPC Linux* cluster including provisioning tools, resource management, I/O clients, development tools, and a variety of scientific libraries. These packages have been pre-built with HPC integration in mind while conforming to common Linux distribution standards. The documentation herein is intended to be reasonably generic, but uses the underlying motivation of a small, 4-node cluster installation to define a step-by-step process. Several optional customizations are included and the intent is that these collective instructions can be modified as needed for local site customizations.

**Base Linux Edition**: this edition of the guide highlights installation without the use of a companion configuration management system and directly uses distro-provided package management tools for component selection. The steps that follow also highlight specific changes to system configuration files that are required as part of the cluster install process.

## 1.1 Target Audience

This guide is targeted at experienced Linux system administrators for HPC environments. Knowledge of software package management, system networking, and PXE booting is assumed. Command-line input examples are highlighted throughout this guide via the following syntax:

```
echo "OpenHPC hello world"
```

Unless specified otherwise, the examples presented are executed with elevated (root) privileges. The examples also presume use of the BASH login shell, though the equivalent commands in other shells can be substituted. In addition to specific command-line instructions called out in this guide, an alternate convention is used to highlight potentially useful tips or optional configuration options. These tips are highlighted via the following format:

**Tip**

Life is a tale told by an idiot, full of sound and fury signifying nothing. –Willy Shakes

## 1.2 Requirements/Assumptions

This installation recipe assumes the availability of a single *head node*, and four *compute* nodes. The *head node* serves as the overall system management server (SMS) and is provisioned with Rocky 10 and is subsequently configured to provision the remaining *compute* nodes with Confluent in a stateless configuration. For power management, we assume that the compute node baseboard management controllers (BMCs) are available via IPMI from the chosen *head node*. For file systems, we assume that the chosen *head node* will host an NFS file system that is made available to the compute nodes.

An outline of the physical architecture discussed is shown in the figure above and highlights the high-level networking configuration. The *head node* requires at least two Ethernet interfaces with *eth0* connected to the local data center network and *eth1* used to provision and manage the cluster backend (note that these interface names are examples and may be different depending on local settings and OS conventions). Two logical IP interfaces are expected to each compute node: the first is the standard Ethernet interface that will be used for provisioning and resource management. The second is used to connect to each host's BMC and is used for power management and remote console access. Physical connectivity for these two logical

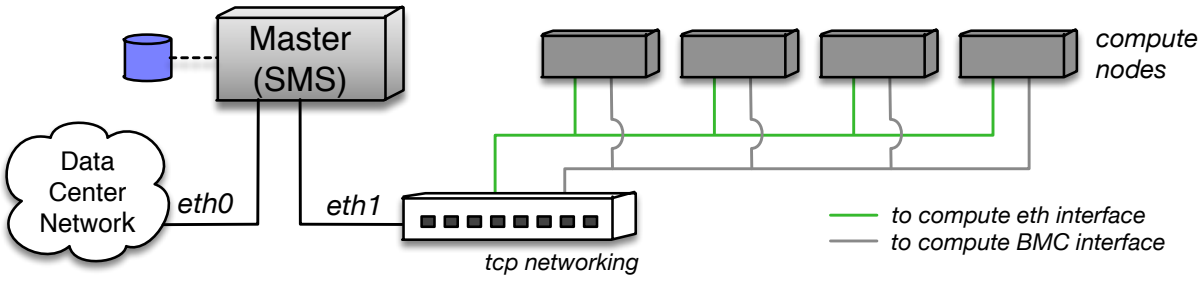



Figure 1: Overview of physical cluster architecture

IP networks is often accommodated via separate cabling and switching infrastructure; however, an alternate configuration can also be accommodated via the use of a shared NIC, which runs a packet filter to divert management packets between the host and BMC. Independent of the actual networking configuration it is recommended to have additional security boundaries like a firewall to protect the network interfaces from the Internet.

## 1.3 Inputs

As this recipe details installing a cluster starting from bare-metal, there is a requirement to define IP addresses and gather hardware MAC addresses in order to support a controlled provisioning process. These values are necessarily unique to the hardware being used, and this document uses variable substitution (`${variable}`) in the command-line examples that follow to highlight where local site inputs are required. A summary of the required and optional variables used throughout this recipe are presented below. Note that while the example definitions above correspond to a small 4-node compute subsystem, the compute parameters are defined in array format to accommodate logical extension to larger node counts.

Required variables:

- `${sms_name}` - Hostname for head node
- `${sms_ip}` - Internal IP address on head node
- `${sms_eth_internal}` - Internal Ethernet interface on head node
- `${internal_network}` - Subnet network address for internal network
- `${internal_netmask}` - Subnet netmask for internal network
- `${internal_prefix_length}` - Subnet prefix length for internal network (e.g. `16`; must be consistent with `${internal_netmask}`)
- `${dns_domain}` - DNS domain name for cluster (e.g. `local`)
- `${ntp_server}` - Local ntp server for time synchronization
- `${bmc_username}` - BMC username for use by IPMI
- `${bmc_password}` - BMC password for use by IPMI
- `${num_computes}` - Total # of desired compute nodes
- `${c_ip[0]}`, `${c_ip[1]}`, … - Desired compute node addresses
- `${c_bmc[0]}`, `${c_bmc[1]}`, … - BMC addresses for computes

- `${c_mac[0]}`, `${c_mac[1]}`, ... - MAC addresses for computes
- `${c_name[0]}`, `${c_name[1]}`, ... - Host names for computes
- `${compute_regex}` - Regex matching all compute node names (e.g. `c*`)
- `${compute_prefix}` - Prefix for compute node names (e.g. `c`)
- `initialize_options` - `usklpta`
- `deployment_protocols` - `firmware`
- `iso_path` - location of compute node base os dvd iso (default: `Rocky-10-latest-aarch64-dvd.iso`)
- `iso_url` - ISO download base URL (optional; overrides default upstream location)

Optional variables:

- `${modules_package}` - Module tool installed on the head node and the computes: `lmod-ohpc` (Lmod, the default) or `environment-modules-ohpc` (Environment Modules)

### 1.4 Installation Template

The collection of command-line instructions that follow in this guide, when combined with local site inputs, can be used to implement a bare-metal system installation and configuration. The format of these commands is intended to be usable via direct cut and paste (with variable substitution for site-specific settings). Alternatively, the OpenHPC documentation package (`docs-ohpc`) includes a template script which includes a summary of all of the commands used herein. This script can be used in conjunction with a simple text file to define the local site variables defined in the previous section (see Requirements/Assumptions) and is provided as a convenience for administrators. For additional information on accessing this script, please see the Automation Appendix.

## 2 Install Base Operating System

### 2.1 Install OS

In an external setting, installing the desired Base OS on a *head node* typically involves booting from a DVD ISO image on a new server. With this approach, insert the Rocky 10 DVD, power cycle the host, and follow the distro provided directions to install the Base OS on your chosen *head node*. Alternatively, if choosing to use a pre-installed server, please verify that it is provisioned with the required Rocky 10 distribution.

Prior to beginning the installation process of OpenHPC components, several additional considerations are noted here for the head node configuration. First, the installation recipe herein assumes that the head node name is resolvable locally. Depending on the manner in which you installed the Base OS, there may be an adequate entry already defined in `/etc/hosts`. If not, add one so the head node resolves itself by name (this guide relies on it for name-based commands):

```
echo ${sms_ip} ${sms_name} >> /etc/hosts
```

While it is theoretically possible to enable SELinux on a cluster provisioned with Confluent, doing so is beyond the scope of this document. Even the use of permissive mode can be problematic and we therefore recommend disabling SELinux on the *head node*. If SELinux components are installed locally, the `selinuxenabled` command can be used to determine if SELinux is currently enabled. If enabled, consult the distro documentation for information on how to disable.

## 2.2 Configure HTTPS Proxy (Optional)

If your environment requires an HTTPS caching proxy for external network access, configure it here before installing any packages.

## 2.3 Enable EL Package Repositories

In addition to the OpenHPC package repository, the *head node* also requires access to the standard base OS distro repositories in order to resolve necessary dependencies. For Rocky 10, the requirements are to have access to the BaseOS, Appstream, Extras, CRB, and EPEL repositories for which mirrors are freely available online:

- Rocky-10 (e.g. http://download.rockylinux.org/pub/rocky/10/)
- EPEL 10 (e.g. http://download.fedoraproject.org/pub/epel/10/)

Although the public EPEL repository would be enabled automatically upon installation of the `ohpc-release` package, we install it now. Note that this does depend on the Rocky 10 Extras repository, which is shipped with Rocky 10 and is typically enabled by default. In contrast, the CRB repository is typically disabled in a standard install, but can be enabled from EPEL as follows:

```
dnf -y install epel-release dnf-plugins-core
dnf config-manager --set-enabled crb
```

## 2.4 Configure Firewall

Provisioning services rely on DHCP, TFTP, and HTTP network protocols. Depending on the local Base OS configuration on the head node, default firewall rules may prohibit these services. Consequently, this recipe assumes that the local firewall running on the head node is disabled (it is still recommended to have additional security boundaries like a firewall to protect the cluster from the Internet). If installed, the default firewall service can be disabled as follows:

```
systemctl disable --now firewalld.service || true
```

## 2.5 Configure NTP

HPC systems rely on synchronized clocks throughout the system and the NTP protocol can be used to facilitate this synchronization. To enable NTP services on the head node with a specific server `${ntp_server}`, and allow this server to serve as a local time server for the cluster, issue the following:

```
dnf -y install chrony
systemctl enable chronyd.service
echo "local stratum 10" >> /etc/chrony.conf
echo "server ${ntp_server}" >> /etc/chrony.conf
echo "allow all" >> /etc/chrony.conf
systemctl restart chronyd.service
```

**Tip**

**Note:** Note that the "allow all" option specified for the chrony time daemon allows all servers on the local network to be able to synchronize with the head node. Alternatively, you can restrict access to fixed IP ranges and an example config line allowing access to a local class B subnet is as follows:

```
allow 192.168.0.0/16
```

## 2.6 Generate SSH Key Pair

An SSH key pair on the *head node* enables passwordless access to compute nodes and is useful for automating cluster configuration tasks.

It is also required by the Confluent provisioner for node deployment.

If an ed25519 key does not already exist, generate one:

```
[[ -f ~/.ssh/id_ed25519 ]] || ssh-keygen -t ed25519 -f ~/.ssh/id_ed25519 -N ''
```

**Tip**

**Note:** The key is generated without a passphrase (`-N ''`) to allow unattended use in scripts and automated workflows. Ensure that access to the head node is appropriately restricted.

## 2.7 Setup NFS Server

Here we set up NFS mounting of a `$HOME` file system and the public OpenHPC install path (`/opt/ohpc/pub`) that will be hosted by the *head node* in this example configuration.

```
# Install and Start NFS server
dnf -y install nfs-utils
systemctl start nfs-server.service

# Create OpenHPC public packages directory
mkdir -p /opt/ohpc/pub

# Export /home and OpenHPC public packages from head node
echo "/home *(rw,no_subtree_check,fsid=10,no_root_squash)" >> /etc/exports
echo "/opt/ohpc/pub *(ro,no_subtree_check,fsid=11)" >> /etc/exports
exportfs -a

# Restart and enable nfs server
systemctl restart nfs-server.service
systemctl enable nfs-server.service
```

## 2.8 Optionally add InfiniBand support services on *head node*

The following command adds OFED and PSM support using base distro-provided drivers to the chosen *head node*.

```
dnf -y groupinstall "InfiniBand Support"
# Load IB services
udevadm trigger --type=devices --action=add
systemctl restart rdma-load-modules@infiniband.service
```

**Tip**

**Note:** InfiniBand networks require a subnet management service that can typically be run on either an administrative node, or on the switch itself. The optimal placement and configuration of the subnet manager is beyond the scope of this document, but Rocky 10 provides the `opensm` package should you choose to run it on the *head node*.

With the InfiniBand drivers included, you can also enable (optional) IPoIB functionality which provides a mechanism to send IP packets over the IB network. If you plan to mount a Lustre file system over InfiniBand, then having IPoIB enabled is a requirement for the Lustre client. The following creates a NetworkManager connection for the IPoIB interface `${ipoib_dev}` on the *head node*, with the address `${sms_ipoib}` and subnet prefix `${ipoib_prefix_length}`. Set `${ipoib_dev}` to the name the system gives the interface, for example `ibp3s0` under predictable interface naming, and add one connection per port if the system contains dual-ported or multiple HCAs.

```
# Define the local IPoIB interface, address, and subnet prefix
nmcli connection add type infiniband con-name ipoib ifname "${ipoib_dev}" \
    ipv4.method manual ipv4.addresses "${sms_ipoib}/${ipoib_prefix_length}"

# Bring up the IPoIB interface
nmcli connection up ipoib
```

## 2.9 Optionally add RoCE support on *head node*

RoCE (RDMA over Converged Ethernet) runs RDMA over Ethernet NICs that support it, for example NVIDIA ConnectX "Dx" models. It uses the same distro-provided RDMA stack as InfiniBand, but it needs no subnet manager and no IPoIB: RDMA traffic is addressed by the Ethernet interface's own IP address. This recipe runs RoCE over the internal cluster network. The following command adds the RDMA stack to the *head node*. If you enabled InfiniBand above, the stack is already installed and the script skips this step.

```
dnf -y groupinstall "InfiniBand Support"
# Load the RDMA drivers for the RoCE NIC
udevadm trigger --type=devices --action=add
systemctl restart rdma-load-modules@rdma.service
```

RoCE takes its own MTU (up to 4096 bytes) from the Ethernet MTU: the largest that fits with room for headers. An Ethernet MTU of 1500 gives RoCE 1024, and exactly 4096 gives only 2048; about 4200 or more (9000 is common) gives the full 4096. RoCE works at the default MTU, and a larger one adds a little bandwidth. Every host and switch port on the network must carry the larger frames.

This recipe leaves the MTU unchanged. To use a larger one, set the same value on the *head node*'s internal interface and on the computes' interfaces in your Confluent network configuration.

### 2.10 Optionally add Omni-Path support services on *head node*

The following command adds Omni-Path support using base distro-provided drivers to the chosen *head node*.

```
dnf -y install opa-basic-tools
```

**Tip**

**Note:** OmniPath networks require a subnet management service that can typically be run on either an administrative node, or on the switch itself. The optimal placement and configuration of the subnet manager is beyond the scope of this document, but Rocky 10 provides the `opa-fm` package should you choose to run it on the *head node*.

**Tip**

**Note:** Many server BIOS configurations have PXE network booting configured as the primary option in the boot order by default. If your compute nodes have a different device as the first in the sequence, the `ipmitool` utility can be used to enable PXE.

```
ipmitool -E -I lanplus -H ${bmc_ipaddr} -U root chassis \
    bootdev pxe options=persistent
```

## 3 Install OpenHPC Components

### 3.1 Enable OpenHPC Repository

With the Base OS installed and booted, the next step is to add desired OpenHPC packages onto the *head node* in order to provide provisioning and resource management services for the rest of the cluster.

To begin, enable use of the OpenHPC repository by adding it to the local list of available package repositories. Note that this requires network access from your *head node* to the OpenHPC repository, or alternatively, that the OpenHPC repository be mirrored locally. In cases where network external connectivity is available, OpenHPC provides an `ohpc-release` package that includes GPG keys for package signing and enabling the repository. The example which follows illustrates installation of the `ohpc-release` package directly from the OpenHPC build server.

```
dnf -y install http://repos.openhpc.community/OpenHPC/4/EL_10/aarch64/\
ohpc-release-4-1.el10.aarch64.rpm
```

**Tip**

**Note:** Many sites may find it useful or necessary to maintain a local copy of the OpenHPC repositories. To facilitate this need, standalone tar archives are provided – one containing a repository of binary packages as well as any available updates, and one containing a repository of source RPMS. The tar files also contain a simple bash script to configure the package manager to use the local repository after download. To use, simply unpack the tarball where you would like to host the local repository and execute the `make_repo.sh` script. Tar files for this release can be found at http://repos.openhpc.community/dist/4.2

### 3.2 Install OpenHPC Base Packages

Now OpenHPC packages can be installed. The `ohpc-base` meta-package requires a module tool to manage the user environment, and OpenHPC provides two of them: Lmod in the `lmod-ohpc` package and Environment Modules in the `environment-modules-ohpc` package. Both read the OpenHPC module hierarchy and provide the `module` command. The `${modules_package}` variable in `input.local` selects the one installed on the head node and, later in this guide, on the compute nodes; it defaults to `lmod-ohpc`. To add the base package and the module tool on the head node issue the following:

```
dnf -y install ohpc-base ${modules_package:-lmod-ohpc}
```

**Tip**

Naming the module tool keeps the choice explicit; `ohpc-base` alone normally pulls in Lmod, which it suggests. The two tools can also be installed side by side: the startup scripts `/etc/profile.d/modules.sh` and `modules.csh`, which define the `module` command, and `/usr/bin/modulecmd` are links managed with `alternatives`, and `environment-modules-ohpc` takes precedence over `lmod-ohpc` when both are present. Run `alternatives --config modules.sh` to select the active tool.

## 4 Install Slurm

### 4.1 Add Slurm on Head Node

The following command adds the Slurm workload manager server components to the chosen *head node*. Note that client-side components will be added to the corresponding compute image in a subsequent step. Note that Slurm leverages the use of the *munge* library to provide authentication services and this daemon also needs to be running on all hosts within the resource management pool.

```
# Install slurm server meta-package
dnf -y install ohpc-slurm-server

# Use ohpc-provided file for starting SLURM configuration
cp /etc/slurm/slurm.conf.ohpc /etc/slurm/slurm.conf

# Setup default cgroups file
cp /etc/slurm/cgroup.conf.example /etc/slurm/cgroup.conf

# Identify resource manager hostname on head node
sed -i "s/SlurmctldHost=\S\+/SlurmctldHost=${sms_name}/" \
    /etc/slurm/slurm.conf
```

There are a wide variety of configuration options and plugins available for Slurm and the example config file illustrated above targets a fairly basic installation. In particular, job completion data will be stored in a text file (`/var/log/slurm_jobcomp.log`) that can be used to log simple accounting information. Sites who desire more detailed information, or want to aggregate accounting data from multiple clusters, will likely want to enable the database accounting back-end. This requires a number of additional local modifications (on top of installing `slurm-slurmdbd-ohpc`), and users are advised to consult the online documentation for more detailed information on setting up a database configuration for Slurm.

**Tip**

**Note:** SLURM requires enumeration of the physical hardware characteristics for compute nodes under its control. In particular, three configuration parameters combine to define consumable compute resources: *Sockets*, *CoresPerSocket*, and *ThreadsPerCore*. The default configuration file provided via OpenHPC assumes the nodes are named c1-c4 and are dual-socket, 8 cores per socket, and two threads per core for this 4-node example. If this does not reflect your local hardware, please update the configuration file at `/etc/slurm/slurm.conf` accordingly to match your nodes names and particular hardware. Be sure to run `scontrol reconfigure` to notify SLURM of the changes. Note that the SLURM project provides an easy-to-use online configuration tool that can be accessed here.

# 5 Install Confluent Provisioner

Installation is accomplished in two steps: First, a generic OS image is installed on *compute* nodes and then, once the nodes are up and running, OpenHPC components are added to both the head node and the nodes at the same time.

## 5.1 Add provisioning services on *head node*

To begin, enable use of the public Confluent repository by adding it to the local list of available package repositories. This also requires network access from your *head node* to the internet, or alternatively, that the repository be mirrored locally. In this case, we use the network. Confluent is pinned at version 3.15.6 by using Lenovo's 26.7.2 release repository in place of `latest`, so that a new Confluent release does not change what this recipe installs.

```
dnf -y install \
https://hpc.lenovo.com/yum/latest/el10/aarch64/lenovo-hpc-yum-1-1.aarch64.rpm
dnf config-manager --save --setopt=lenovo-hpc.baseurl=\
https://hpc.lenovo.com/yum/26.7.2/el10/aarch64/
```

With the Confluent repository enabled, issue the following to install the provisioning service on the *head node*:

```
# Install Confluent and required packages (rsync: syncfiles and nodersync)
dnf -y install lenovo-confluent
dnf -y install tftp-server nfs-utils policycoreutils-python-utils yq jq rsync
dnf -y install confluent_ipxe-aarch64 confluent_osdeploy-aarch64-3.15.6

# Enable Confluent and its tools for use in current shell
systemctl enable --now confluent.service
systemctl enable --now httpd.service
setsebool -P httpd_can_network_connect on
semanage fcontext -a -t httpd_sys_content_t '/var/lib/confluent(/.*)?'
systemctl enable --now tftp.socket

# Source the confluent profile to setup env
source /etc/profile.d/confluent_env.sh
```

## 5.2 Complete Basic Confluent Setup for the Head Node

At this point, all of the packages necessary to use Confluent on the *head* node should be installed. Confluent requires a network domain name specification for system-wide name resolution. This value can be set to match your local DNS schema or given a unique identifier such as `local`. A default group called everything is automatically added to every node. It provides a method to indicate global settings. Attributes may all be specified on the command line, and an example set could be:

```
nodegroupattrib everything \
    deployment.useinsecureprotocols=${deployment_protocols:-firmware} \
    dns.domain=${dns_domain:-local}
nodegroupattrib everything \
    dns.servers=${dns_servers} net.ipv4_gateway=${ipv4_gateway}
```

## 5.3 Download ISO Image for Compute Node Deployment

The `osdeploy import` command (below) requires a local copy of the Rocky 10 ISO image (`Rocky-10-latest-aarch64-dvd.is` available from the Rocky 10 download page. The ISO is expected at `${iso_path}`, which defaults to `Rocky-10-latest-aarch64-dvd.iso` in the current directory. If it is not already present, download it:

```
iso_file="Rocky-10-latest-aarch64-dvd.iso"
iso_url="${iso_url:=https://dl.rockylinux.org/pub/rocky/10/isos/aarch64}"
: "${iso_path:=${iso_file}}"
[[ -f "${iso_path}" ]] || curl -fo "${iso_path}" "${iso_url}/${iso_file}"
```

## 5.4 Build Initial Compute Base OS image

With the provisioning services enabled, the next step is to define a system image that can subsequently be used to provision one or more *compute* nodes. To begin, you will first need to have a local copy of the ISO image available for the underlying OS. In this recipe, the relevant ISO image is `Rocky-10-latest-aarch64-dvd.iso` (available from the Rocky 10 download page). We initialize the image creation process using the `osdeploy` command assuming that the necessary ISO image is available locally in `${iso_path}` as follows:

The `osdeploy initialize` command is used to prepare a Confluent server to deploy operating systems. For first time setup, run osdeploy initialize interactively to be walked through the various options using: `osdeploy initialize -i`

```
osdeploy initialize -${initialize_options:-usklpta}
: "${iso_path:=Rocky-10-latest-aarch64-dvd.iso}"
distro_id=$(osdeploy importcheck "${iso_path}" 2>&1 \
    | sed -En 's/Detected distribution name: (.*)/\1-default/p')
osdeploy import "${iso_path}"
restorecon -Rv /var/lib/confluent/
```

Once completed, the OS image should be available for use within Confluent. These can be queried via:

```
# Query available images
osdeploy list
```

We now update the kernel arguments to remove the `quiet` option and add serial console. You could also add `debug` here as well to increase debug messages.

```
# Update kernel arguments: drop quiet, add serial console
yq -i '.kernelargs |= sub("quiet ?", "")' \
  /var/lib/confluent/public/os/${distro_id}/profile.yaml
yq -i ".kernelargs += \" console=tty0 console=ttyAMA0,115200 rd.shell\"" \
  /var/lib/confluent/public/os/${distro_id}/profile.yaml
osdeploy updateboot ${distro_id}
```

If needing to copy files from the head node to the compute nodes during deployment, this can be done by modifying the syncfiles file that is created when `osdeploy import` command is run. For an environment that has no DNS server and needs to have /etc/hosts file synced amongst all the nodes, the following command should be run.

```
echo "/etc/hosts -> /etc/hosts" >> \
    /var/lib/confluent/public/os/${distro_id}/syncfiles
```

If IPoIB will be configured on the compute nodes (see below), add `rdma-core` to the image's package list: Confluent configures only the interfaces present when a node first boots, and a minimal install lacks the package that loads the IPoIB driver.

```
echo rdma-core >> /var/lib/confluent/public/os/${distro_id}/packagelist
```

## 5.5 Add Compute Nodes

Next, we add *compute* nodes to the and define their properties as attributes in the Confluent database. These hosts are grouped logically into a group named *compute* to facilitate group-level commands used later

in the recipe. The compute group has to be defined first before we can add any nodes to the group using the `nodegroup define` command. Note the use of variable names for the desired compute hostnames, node IPs, MAC addresses, and BMC login credentials, which should be modified to accommodate local settings and hardware. To enable serial console access via Confluent, `console.method` property is also defined.

```
# Define the compute group
nodegroupdefine compute

# Define nodes as objects in Confluent database
for ((i=0; i<$num_computes; i++)) ; do
    nodedefine ${c_name[$i]} groups=everything,compute \
    hardwaremanagement.manager=${c_bmc[$i]} \
    secret.hardwaremanagementuser=${bmc_username} \
    secret.hardwaremanagementpassword=${bmc_password} \
    net.hwaddr=${c_mac[$i]} net.bootable=true net.ipv4_method=static \
    net.ipv4_address=${c_ip[$i]}/${internal_prefix_length}
done
```

**Tip**

Defining nodes one-by-one, as done above, is only efficient for a small number of nodes. For larger node counts, Confluent provides capabilities for automated detection and configuration. Consult the Confluent Hardware Discovery & Define Node Guide.

`confluent2hosts` can be used to help generate /etc/hosts entries for a noderange. It can read from the Confluent database, using -a. In this mode, each net.value.attribute group is pulled together into hosts lines. ipv4 and ipv6 address fields are associated with the corresponding hostname attributes.

```
# Add nodes to /etc/hosts
confluent2hosts -a compute
```

With the desired compute nodes and domain identified, the remaining steps in the provisioning configuration process are to define the provisioning mode and image for the *compute* group and use Confluent commands to complete configuration for network services like DNS and DHCP. These tasks are accomplished as follows:

```
# Associate desired provisioning image for computes
nodedeploy -n compute -p ${distro_id}
```

## 5.6 Optionally configure IPoIB on *compute nodes*

To use IPoIB on the compute nodes (required if planning to mount Lustre/BeeGFS over IB; see Optionally add InfiniBand support services on *head node*), give each compute its own address `${c_ipoib[i]}` on the IPoIB interface `${ipoib_dev}`, with the `${ipoib_netmask}` netmask (`${ipoib_prefix_length}` prefix). These are per-node settings, so they belong in the Confluent node definitions:

```
# Register desired IPoIB IPs per compute
for ((i=0; i<num_computes; i++)) ; do
    nodeattrib "${c_name[$i]}" net.ib.interface_names="${ipoib_dev}" \
        net.ib.ipv4_address="${c_ipoib[$i]}/${ipoib_prefix_length}"
done
```

## 5.7 Boot Compute Nodes

Prior to booting the *compute* hosts, we configure them to use PXE as their next boot mode. After the initial PXE, ensuing boots will return to using the default boot device specified in the BIOS.

```
nodesetboot compute network
```

At this point, the *head node* should be able to boot the newly defined compute nodes. This is done by using the `nodepower` Confluent command leveraging IPMI protocol set up during the *compute* node definition in the previous section. The following power cycles each of the desired hosts. Without a BMC (`has_ipmi=0`), the recipe instead prints one `ohpc_reset` line per node for an external reset handler, as the other provisioners' boot steps do.

```
nodepower compute boot
```

Once kicked off, the boot process should take about 5-10 minutes (depending on BIOS post times). You can monitor the provisioning by using the `nodeconsole` command, which displays serial console for a selected node. Note that the escape sequence is `CTRL-e c .` typed sequentially.

Successful provisioning can be verified by a parallel command on the compute nodes. The Confluent-provided `nodeshell` command uses Confluent node names and groups. For example, to run a command on the newly imaged compute hosts using `nodeshell`, execute the following:

```
nodeshell compute uptime
c1:  12:56:50 up 14 min,  0 users,  load average: 0.00, 0.01, 0.04
c2:  12:56:50 up 13 min,  0 users,  load average: 0.00, 0.02, 0.05
c3:  12:56:50 up 14 min,  0 users,  load average: 0.00, 0.02, 0.05
c4:  12:56:50 up 14 min,  0 users,  load average: 0.00, 0.01, 0.04
```

Continue after the deployment completes on every compute node: `nodedeploy` reports each node as `completed` once its install has finished. To check one node:

```
nodedeploy ${compute_prefix}1
```

## 5.8 Wait for Compute Nodes

Continue after the compute nodes boot and complete their install. A node has booted when `systemd` has finished starting it, and reports `running`, or `degraded` if a unit failed. To check one node, and to list its failed units:

```
ssh ${compute_prefix}1 systemctl is-system-running
ssh ${compute_prefix}1 systemctl --failed
```

A node that never answers has failed to provision; check its console.

## 5.9 Setup Compute Nodes

We now need to configure the compute nodes. We leverage the Confluent-provided `nodeshell` command that runs the command on the `compute` nodes.

We first disable the firewall on the compute nodes.

```
# Disable firewall for computes
nodeshell compute systemctl disable --now firewalld.service
```

We next add the kernel drivers.

```
# Add kernel drivers
nodeshell compute dnf -y install kernel
```

The *compute* nodes need access to the EPEL repository, a required dependency for OpenHPC packages.

```
# Add EPEL repo
nodeshell compute dnf -y install epel-release
# Enable CRB
nodeshell compute "/usr/bin/crb enable"
```

And add additional packages, with the head node as the compute nodes' time server.

```
# Add Network Time Protocol (NTP) support, synchronized to the head node
nodeshell compute dnf -y install chrony
nodeshell compute "echo server ${sms_ip} iburst >> /etc/chrony.conf"
nodeshell compute "systemctl restart chronyd.service"

# Include nfs-utils
nodeshell compute dnf -y install nfs-utils
```

## 5.10 Deploy OpenHPC Components on Compute Notes

The next step is adding OpenHPC components to the *compute* nodes that at this point are running basic OSes. This process will leverage two Confluent-provided commands: `nodeshell` to run the package installer on all the nodes in parallel and `nodersync` to distribute configuration files from the head node to the *compute* nodes.

We first add the OpenHPC repository to the compute nodes:

```
# Add OpenHPC repo
nodeshell compute dnf -y install \
    http://repos.openhpc.community/OpenHPC/4/EL_10/aarch64/\
ohpc-release-4-1.el10.aarch64.rpm
```

Additionally, a workaround is needed for OpenHPC documentation files, which are installed into a read-only NFS share /opt/ohpc/pub. Any package attempting to write to that directory will fail to install. The following prevents that by directing `rpm` not to install documentation files on the *compute* nodes:

```
nodeshell compute 'echo "%_excludedocs 1" >> \
  "$HOME/.rpmmacros"'
```

Now OpenHPC and other cluster-related software components can be installed on the nodes. The first step is to install a base compute package on the compute nodes:

```
# Install compute node base meta-package
nodeshell compute dnf -y install ohpc-base-compute
```

Next, we can include additional components, starting with the module tool selected with `${modules_package}`, as on the head node:

```
# Include modules user environment
nodeshell compute dnf -y install ${modules_package:-lmod-ohpc}
```

### 5.11 Install Slurm

In the previous section, the Slurm resource manager was installed and configured on the *head node*.

We now install the Slurm clients and configure them. The Slurm and `munge` configuration files need to be copied to the nodes. This can be accomplished as follows:

```
# Add Slurm client support meta-package
nodeshell compute dnf -y install ohpc-slurm-client
```

Copy the `slurm.conf` and munge keys to the compute nodes.

```
nodersync /etc/slurm/slurm.conf compute:/etc/slurm/slurm.conf
nodersync /etc/munge/munge.key compute:/etc/munge/munge.key
```

### 5.12 Configure NFS Mounts on Compute Nodes

Configure NFS mounts to access the *head node*'s shared filesystems on *compute* nodes.

```
# Add NFS mounts for /home and /opt/ohpc/pub
MOUNT_OPTIONS="nfsvers=3,nodev,nosuid 0 0"
NFS_PUB="${sms_ip}:/opt/ohpc/pub /opt/ohpc/pub nfs ${MOUNT_OPTIONS}"
nodeshell compute "echo ${sms_ip}:/home /home nfs ${MOUNT_OPTIONS} >> /etc/fstab"
nodeshell compute "echo ${NFS_PUB} >> /etc/fstab"
# Create mount point and mount filesystems
nodeshell compute "mkdir -p /opt/ohpc/pub"
nodeshell compute "mount -a"
```

## 6 Additional Customization

This chapter highlights common additional customizations that can *optionally* be applied to the local cluster environment. Details on the steps required for each of these customizations are discussed further in the following sections.

## 6.1 Enable InfiniBand drivers

If your compute resources support InfiniBand, the following commands add OFED and PSM support using base distro-provided drivers to the compute image.

```
# Add IB support and enable
nodeshell compute "dnf -y groupinstall 'InfiniBand Support'"
```

## 6.2 Enable RoCE drivers

If your compute resources support RoCE, the following commands add the same RDMA stack to the compute image. If you enabled InfiniBand drivers above, the stack is already there and the script skips the install.

```
# Add RDMA support
nodeshell compute "dnf -y groupinstall 'InfiniBand Support'"
```

To run MPI over RoCE, select the RDMA device and port for UCX, for example `UCX_NET_DEVICES=mlx5_1:1`; `rdma link` lists each RDMA device with its network interface.

## 6.3 Enable Omni-Path drivers

If your compute resources support Omni-Path, the following commands add OPA support using base distro-provided drivers to the compute image.

```
# Add OPA support and enable
nodeshell compute dnf -y install opa-basic-tools
nodeshell compute dnf -y install libpsm2
```

## 6.4 Increase locked memory limits

In order to utilize InfiniBand or Omni-Path as the underlying high speed interconnect, it is generally necessary to increase the locked memory settings for system users. This can be accomplished by adding the `/etc/security/limits.d/40-ohpc-limits.conf` file and this should be performed on all job submission hosts. In this recipe, jobs are submitted from the *head node*, and the following commands can be used to update the maximum locked memory settings on both the *head node* and compute nodes:

```
# Update memlock settings on head node
echo '* soft memlock unlimited' >> \
  /etc/security/limits.d/40-ohpc-limits.conf
echo '* hard memlock unlimited' >> \
  /etc/security/limits.d/40-ohpc-limits.conf

# Update memlock settings on compute
nodeshell compute 'echo "* soft memlock unlimited" >> \
  "/etc/security/limits.d/40-ohpc-limits.conf"'
nodeshell compute 'echo "* hard memlock unlimited" >> \
  "/etc/security/limits.d/40-ohpc-limits.conf"'
```

## 6.5 Enable ssh control via resource manager

An additional optional customization that is recommended is to restrict `ssh` access on compute nodes to only allow access by users who have an active job associated with the node. This can be enabled via the use of a pluggable authentication module (PAM) provided as part of the Slurm package installs. To enable this feature on *compute* nodes, issue the following:

```
nodeshell compute 'echo "account    required     pam_slurm.so" >> \
  "/etc/pam.d/sshd"'
```

## 6.6 NVIDIA GPU Drivers

To add the optional NVIDIA GPU driver to the compute nodes, an additional external dnf repository provided by NVIDIA must be configured. Once the repository is configured, the GPU driver needs to be installed on the compute image and the corresponding toolkit installed on the head node.

OpenHPC provides a convenience package to enable the NVIDIA repository locally along with compatibility packages that integrate the NVIDIA HPC SDK within the standard OpenHPC user environment.

**Tip**

**Note:** The driver is NVIDIA's open GPU kernel module (`kmod-nvidia-open-dkms`), the only kernel module in NVIDIA's EL10 repository. It supports GPUs of the Turing architecture and newer.

```
# Add NVIDIA GPU driver repository to the head node
dnf -y install cuda-repo-ohpc

# Add NVIDIA GPU driver repository to the compute nodes
nodeshell compute dnf -y install cuda-repo-ohpc

# Install the GPU driver on the compute nodes
nodeshell compute dnf -y install nvidia-driver-cuda kmod-nvidia-open-dkms

# Build the driver for the image's kernel (DKMS otherwise targets the running kernel)
nodeshell compute "dkms autoinstall -k \$(ls /lib/modules | sort -V | tail -n 1)"

# Enable DKMS service to automatically rebuild driver
nodeshell compute "systemctl enable --now dkms.service"

# Install the toolkit on the head node
dnf -y install cuda-devel-ohpc
```

## 6.7 Enable System Log Forwarding

It is often desirable to consolidate system logging information for the cluster in a central location, both to provide easy access to the data, and to reduce the impact of storing data inside the compute node's memory footprint if it is stateless. The following commands highlight the steps necessary to configure compute nodes to forward their logs to the head node, and to allow the head node to accept these log requests.

```
# Configure head node to receive messages and reload rsyslog configuration
echo 'module(load="imudp")' >> /etc/rsyslog.d/ohpc.conf
echo 'input(type="imudp" port="514")' >> /etc/rsyslog.d/ohpc.conf
systemctl restart rsyslog.service

# Define compute node forwarding destination
nodeshell compute "echo '*.* @${sms_ip}:514' > /etc/rsyslog.d/ohpc-forward.conf"

# Disable most local logging on computes.
# Emergency and boot logs will remain on the compute nodes
nodeshell compute sed -i 's/^\*\.info/#\*\.info/' \
  "/etc/rsyslog.conf"
nodeshell compute sed -i 's/^authpriv/#authpriv/' \
  "/etc/rsyslog.conf"
nodeshell compute sed -i 's/^mail/#mail/' \
  "/etc/rsyslog.conf"
nodeshell compute sed -i 's/^cron/#cron/' \
  "/etc/rsyslog.conf"
nodeshell compute sed -i 's/^uucp/#uucp/' \
  "/etc/rsyslog.conf"

# Let the compute nodes pick up the new configuration
nodeshell compute "systemctl restart rsyslog.service"
```

## 6.8 Cluster Admin Tools

### 6.8.1 Add ClusterShell

ClusterShell is an event-based Python library to execute commands in parallel across cluster nodes. Installation and basic configuration defining three node groups (*adm*, *compute*, and *all*) is as follows:

```
# Install ClusterShell
dnf -y install clustershell

# Setup node definitions
mv /etc/clustershell/groups.d/local.cfg \
   /etc/clustershell/groups.d/local.cfg.orig
echo "adm: ${sms_name}" > \
  /etc/clustershell/groups.d/local.cfg
echo "compute: ${compute_prefix}[1-${num_computes}]" >> \
  /etc/clustershell/groups.d/local.cfg
echo "all: @adm,@compute" >> \
  /etc/clustershell/groups.d/local.cfg
```

### 6.8.2 Add genders

genders is a static cluster configuration database or node typing database used for cluster configuration management. Other tools and users can access the genders database in order to make decisions about where an action, or even what action, is appropriate based on associated types or "genders". Values may also be assigned to and retrieved from a *gender* to provide further granularity. The following example highlights installation and configuration of two genders: *compute* and *bmc*.

```
# Install genders
dnf -y install genders-ohpc

# Generate a sample genders file
echo -e "${sms_name}\tsms" > /etc/genders
for ((i=0; i<num_computes; i++)) ; do
          echo -e "${c_name[$i]}\tcompute,bmc=${c_bmc[$i]}"
    done >> /etc/genders
```

### 6.8.3 Add ConMan

conman is a serial console management program designed to support a large number of console devices and simultaneous users. It supports logging console device output and connecting to compute node consoles via IPMI serial-over-lan. Installation and example configuration is outlined below.

```
# Install conman to provide a front-end to compute consoles and log output
dnf -y install conman-ohpc

# Configure conman for computes
# (note your IPMI password is required for console access)
for ((i=0; i<num_computes; i++)) ; do
    echo -n 'CONSOLE name="'"${c_name[$i]}"'" dev="ipmi:'"${c_bmc[$i]}"'" '
    echo -n 'ipmiopts="'U:"${bmc_username}",P:
    echo "${IPMI_PASSWORD:-undefined}",W:solpayloadsize'"'
    done >> /etc/conman.conf

# Enable and start conman
systemctl enable conman.service
systemctl start conman.service
```

### 6.8.4 Add NHC

Resource managers often provide for a periodic "node health check" to be performed on each compute node to verify that the node is working properly. Nodes which are determined to be "unhealthy" can be marked as down or offline so as to prevent jobs from being scheduled or run on them. This helps increase the reliability and throughput of a cluster by reducing preventable job failures due to misconfiguration, hardware failure, etc. OpenHPC distributes `nhc` to fulfill this requirement.

In a typical scenario, the `nhc` driver script is run periodically on each compute node by the resource manager client daemon. It loads its configuration file to determine which checks are to be run on the current node (based on its hostname). Each matching check is run, and if a failure is encountered, `nhc` will exit with an error message describing the problem. It can also be configured to mark nodes offline so that the scheduler will not assign jobs to bad nodes, reducing the risk of system-induced job failures.

```
# Install NHC on head and compute nodes
dnf -y install nhc-ohpc
nodeshell compute dnf -y install nhc-ohpc
```

```
# Register as SLURM's health check program
echo "HealthCheckProgram=/usr/sbin/nhc" >> /etc/slurm/slurm.conf

# execute every five minutes
echo "HealthCheckInterval=300" >> /etc/slurm/slurm.conf
```

### 6.9 Add Magpie

Magpie contains a number of scripts to aid in running a variety of big data software frameworks within HPC queuing environments. Examples include Hadoop, Spark, Hbase, Storm, Pig, Mahout, Phoenix, Kafka, Zeppelin, and Zookeeper. Consult the online repository for more information on using these scripts; basic installation is outlined as follows:

```
# Install magpie
dnf -y install magpie-ohpc
```

### 6.10 Charliecloud

Typical Charliecloud workflows are based around Docker containers, but it is not strictly necessary to install Docker itself on the HPC resource. A common pattern is to build the Docker container on a laptop or VM and upload the result to the cluster for use with Charliecloud. More information can be found at https://hpc.github.io/charliecloud/

## 7 Deploy Cluster

### 7.1 Start Slurm

In an earlier section, the Slurm resource manager was installed and configured for use on both the *head node* and *compute* node instances. With the cluster nodes up and functional, we can now startup the resource manager services in preparation for running user jobs.

```
# Start munge and slurm controller on head node
systemctl enable --now munge.service
systemctl enable --now slurmctld.service
```

Running systems may need to restart `slurmctld` to pickup any changes.

### 7.2 Start Slurm on Compute Nodes

With Slurm configured, we can now startup the resource manager services in preparation for running user jobs. Generally, this is a two-step process that requires starting up the controller daemons on the *head node* and the client daemons on each of the *compute* nodes. Note that Slurm leverages the use of the *munge* library to provide authentication services and this daemon also needs to be running on all hosts within the resource management pool.

We now start the Slurm daemon on the compute nodes.

```
# Start munge and slurm controller on head node
nodeshell compute "systemctl enable --now munge.service"
nodeshell compute "systemctl enable --now slurmd.service"
```

After this, check status of the nodes within Slurm by using the `sinfo` command. All compute nodes should be in an *idle* state (without asterisk). If the state is reported as *unknown*, the following might help:

```
scontrol update partition=normal state=idle
```

In case of additional Slurm issues, ensure that the configuration file fits your hardware and that it is identical across the nodes. Also, verify that Slurm user id is the same on the *head node* and *compute* nodes. You may also consult Slurm Troubleshooting Guide.

# 8 Install OpenHPC Development Components

The install procedure outlined in Install OpenHPC Components highlighted the steps necessary to install a *head node*, assemble and customize a *compute* image, and provision several compute hosts from bare-metal. With these steps completed, additional OpenHPC-provided packages can now be added to support a flexible HPC development environment including development tools, C/C++/FORTRAN compilers, MPI stacks, and a variety of 3rd party libraries. The following subsections highlight the additional software installation procedures.

## 8.1 Development Tools

To aid in general development efforts, OpenHPC provides recent versions of the GNU autotools collection, the Valgrind memory debugger, EasyBuild, and Spack. These can be installed as follows:

```
# Install autotools meta-package
dnf -y install ohpc-autotools
dnf -y install EasyBuild-ohpc
dnf -y install hwloc-ohpc
dnf -y install spack-ohpc
dnf -y install valgrind-ohpc
```

## 8.2 Compilers

OpenHPC presently packages the GNU compiler toolchain integrated with the underlying environment modules system in a hierarchical fashion. The modules system will conditionally present compiler-dependent software based on the toolchain currently loaded.

```
dnf -y install gnu16-compilers-ohpc
```

## 8.3 MPI Stacks

For MPI development and runtime support, OpenHPC provides pre-packaged builds for a variety of MPI families and transport layers. Currently available options and their applicability to various network transports are summarized in the Available MPI variants table below. The command that follows installs a starting set of MPI families that are compatible with both ethernet and high-speed fabrics.

**Table: Available MPI builds**

| | Ethernet (TCP) | InfiniBand |
|---|---|---|
| MPICH | ✓ | |
| OpenMPI | ✓ | ✓ |

```
dnf -y install openmpi5-pmix-gnu16-ohpc mpich-ofi-gnu16-ohpc
```

Note that the MPICH and OpenMPI builds support two related transport layers for a variety of underlying fabrics: UCX (Unified Communication X) and OFI (OpenFabrics interfaces). In the case of OpenMPI, a monolithic build is provided which supports both transports and end-users can customize their runtime preferences with environment variables. For MPICH, two separate builds are provided and the example above highlighted installing the `ofi` variant. However, the packaging is designed such that both versions can be installed simultaneously and users can switch between the two via normal module command semantics. Alternatively, a site can choose to install the `ucx` variant instead as a drop-in MPICH replacement:

```
dnf -y install mpich-ucx-gnu16-ohpc
```

In the case where both MPICH variants are installed, two modules will be visible in the end-user environment and an example of this configuration is highlighted is below.

```
module avail mpich

-------------------- /opt/ohpc/pub/moduledeps/gnu16---------------------
   mpich/3.4.3-ofi    mpich/3.4.3-ucx (D)
```

## 8.4 Performance Tools

OpenHPC provides a variety of open-source tools to aid in application performance analysis (refer to Package Manifest for a listing of available packages). This group of tools can be installed as follows:

```
# Install perf-tools meta-package
dnf -y install ohpc-gnu16-perf-tools
```

## 8.5 Setup default development environment

System users often find it convenient to have a default development environment in place so that compilation can be performed directly for parallel programs requiring MPI. This setup can be conveniently enabled via modules and the OpenHPC modules environment is pre-configured to load an `ohpc` module on login (if present). The following package install provides a default environment that enables autotools, the GNU compiler toolchain, and the OpenMPI stack.

```
dnf -y install modules-defaults-gnu16-openmpi5-ohpc
```

**Tip**

If you want to change the default environment from the suggestion above, OpenHPC also provides additional default options using the GNU compiler toolchain with multiple MPICH variants. Relevant modules-default packages names are as follows:

- modules-defaults-gnu16-mpich-ofi-ohpc
- modules-defaults-gnu16-mpich-ucx-ohpc

## 8.6 3rd Party Libraries and Tools

OpenHPC provides pre-packaged builds for a number of popular open-source tools and libraries used by HPC applications and developers. For example, OpenHPC provides builds for FFTW and HDF5 (including serial and parallel I/O support), and the GNU Scientific Library (GSL). Again, multiple builds of each package are available in the OpenHPC repository to support multiple compiler and MPI family combinations where appropriate. Note, however, that not all combinatorial permutations may be available for components where there are known license incompatibilities. The general naming convention for builds provided by OpenHPC is to append the compiler and MPI family name that the library was built against directly into the package name. For example, libraries that do not require MPI as part of the build process adopt the following RPM name:

```
package-<compiler_family>-ohpc-<package_version>-<release>.rpm
```

Packages that do require MPI as part of the build expand upon this convention to additionally include the MPI family name as follows:

```
package-<compiler_family>-<mpi_family>-ohpc-<package_version>-<release>.rpm
```

To illustrate this further, the command below queries the locally configured repositories to identify all of the available PETSc packages that were built with the GNU toolchain. The resulting output that is included shows that pre-built versions are available for each of the supported MPI families presented in MPI Stacks.

```
dnf search petsc-gnu16 ohpc
Loaded plugins: fastestmirror
Loading mirror speeds from cached hostfile
============================ N/S matched: petsc-gnu16, ohpc ============================
petsc-gnu16-mpich-ohpc.x86_64 : Portable Extensible Toolkit for Scientific Computation
petsc-gnu16-openmpi5-ohpc.x86_64 : Portable Extensible Toolkit for Scientific Comp...
```

**Tip**

OpenHPC-provided 3rd party builds are configured to be installed into a common top-level repository so that they can be easily exported to desired hosts within the cluster. This common top-level path (`/opt/ohpc/pub`) was previously configured to be mounted on **compute** nodes in an earlier section, so the packages will be immediately available for use on the cluster after installation on the **head node**.

For convenience, OpenHPC provides package aliases for these 3rd party libraries and utilities that can be used to install available libraries for use with the GNU compiler family toolchain. For parallel libraries, aliases are grouped by MPI family toolchain so that administrators can choose a subset should they favor a

particular MPI stack. Please refer to the Package Manifest appendix for a more detailed listing of all available packages in each of these functional areas. To install all available package offerings within OpenHPC, issue the following:

```
# Install 3rd party libraries/tools meta-packages built with GNU toolchain
dnf -y install ohpc-gnu16-serial-libs
dnf -y install ohpc-gnu16-io-libs
dnf -y install ohpc-gnu16-python-libs
dnf -y install ohpc-gnu16-runtimes
```

```
# Install parallel lib meta-packages for all available MPI toolchains
dnf -y install ohpc-gnu16-mpich-parallel-libs
dnf -y install ohpc-gnu16-openmpi5-parallel-libs
```

# 9 Post Provisioning

## 9.1 Check Cluster Status

After this, check status of the nodes within Slurm by using the `sinfo` command. Continue after every compute node is in an *idle* state (without asterisk). To check one node:

```
sinfo -N -n ${compute_prefix}1
```

If the state is reported as *unknown*, the following might help:

```
scontrol update partition=normal state=idle
```

In case of additional Slurm issues, ensure that the configuration file fits your hardware and that it is identical across the nodes. Also, verify that the Slurm user id is the same on the head node and *compute* nodes. You may also consult Slurm Troubleshooting Guide.

## 9.2 Add User

We will now add a new user to the cluster. This will be used later to run a test job.

```
useradd -m test
```

Next, the user's credentials need to be distributed across the cluster. Confluent's `nodeapply` has a merge functionality that adds new entries into credential files on *compute* nodes:

```
# Create a sync file for pushing user credentials to the nodes
echo "/etc/passwd -> /etc/passwd" >> \
    /var/lib/confluent/public/os/${distro_id}/syncfiles
echo "/etc/group -> /etc/group" >> \
    /var/lib/confluent/public/os/${distro_id}/syncfiles

# Use Confluent to distribute credentials to nodes
nodeapply -F compute
```

### 9.3 Update NHC

Generate NHC configuration file based on compute node environment

```
nodeshell c1 "/usr/sbin/nhc-genconf -H '*' -c -" | dshbak -c
```

## 10 Test Cluster

We now run some simple tests on the cluster to ensure it is operational.

### 10.1 Run a Test Job

With the resource manager enabled for production usage, users should now be able to run jobs. To demonstrate this, we will add a "test" user on the **head** node that can be used to run an example job.

OpenHPC includes a simple "hello-world" MPI application in the `/opt/ohpc/pub/examples` directory that can be used for this quick compilation and execution. OpenHPC also provides a companion job-launch utility named `prun` that is installed in concert with the pre-packaged MPI toolchains. This convenience script provides a mechanism to abstract job launch across different resource managers and MPI stacks such that a single launch command can be used for parallel job launch in a variety of OpenHPC environments. It also provides a centralizing mechanism for administrators to customize desired environment settings for their users.

### 10.2 Interactive Execution

To use the newly created "test" account to compile and execute the application **interactively** through the resource manager, execute the following (note the use of `prun` for parallel job launch which summarizes the underlying native job launch mechanism being used):

```
# Switch to "test" user
su - test

# Compile MPI "hello world" example
[test@sms ~]$ mpicc -O3 /opt/ohpc/pub/examples/mpi/hello.c

# Submit interactive job request and use prun to launch executable
[test@sms ~]$ salloc -n 8 -N 2

[test@c1 ~]$ prun ./a.out

[prun] Master compute host = c1
[prun] Resource manager = slurm
[prun] Launch cmd = mpiexec.hydra -bootstrap slurm ./a.out

 Hello, world (8 procs total)
    --> Process #   0 of   8 is alive. -> c1
    --> Process #   4 of   8 is alive. -> c2
    --> Process #   1 of   8 is alive. -> c1
    --> Process #   5 of   8 is alive. -> c2
    --> Process #   2 of   8 is alive. -> c1
    --> Process #   6 of   8 is alive. -> c2
    --> Process #   3 of   8 is alive. -> c1
    --> Process #   7 of   8 is alive. -> c2
```

**Tip**

The following table provides approximate command equivalences between SLURM and OpenPBS:

| Command | OpenPBS | SLURM |
|---|---|---|
| Submit *batch* job | qsub [job script] | sbatch [job script] |
| Request *interactive* shell | qsub -I /bin/bash | salloc |
| Delete job | qdel [job id] | scancel [job id] |
| Queue status | qstat -q | sinfo |
| Job status | qstat -f [job id] | scontrol show job [job id] |
| Node status | pbsnodes [node name] | scontrol show node [node id] |

## 10.3 Batch execution

For batch execution, OpenHPC provides a simple job script for reference (also housed in the `/opt/ohpc/pub/examples` directory. This example script can be used as a starting point for submitting batch jobs to the resource manager and the example below illustrates use of the script to submit a batch job for execution using the same executable referenced in the previous interactive example.

```
# Copy example job script
[test@sms ~]$ cp /opt/ohpc/pub/examples/slurm/job.mpi .

# Examine contents (and edit to set desired job sizing characteristics)
[test@sms ~]$ cat job.mpi
#!/bin/bash

#SBATCH -J test              # Job name
#SBATCH -o job.%j.out        # Name of stdout output file (%j expands to %jobId)
#SBATCH -N 2                 # Total number of nodes requested
#SBATCH -n 16                # Total number of mpi tasks #requested
#SBATCH -t 01:30:00          # Run time (hh:mm:ss) - 1.5 hours

# Launch MPI-based executable

prun ./a.out

# Submit job for batch execution
[test@sms ~]$ sbatch job.mpi
Submitted batch job 339
```

**Tip**

The use of the `%j` option in the example batch job script shown is a convenient way to track application output on an individual job basis. The `%j` token is replaced with the Slurm job allocation number once assigned (job #339 in this example).

# Appendices

## A Installation Template

This appendix highlights the availability of a companion installation script that is included with OpenHPC documentation. This script, when combined with local site inputs, can be used to implement a starting recipe for bare-metal system installation and configuration. This template script is used during validation efforts to test cluster installations and is provided as a convenience for administrators as a starting point for potential site customization.

**Tip**

Note that the template script provided is intended for use during initial installation and is not designed for repeated execution. If modifications are required after using the script initially, we recommend running the relevant subset of commands interactively.

The template script relies on the use of a simple text file to define local site variables that were outlined in the Inputs section. By default, the template installation script attempts to use local variable settings sourced from the `/opt/ohpc/pub/doc/recipes/vanilla/input.local` file, however, this choice can be overridden by the use of the `${OHPC_INPUT_LOCAL}` environment variable. The template install script is intended for execution on the **head node** and is installed as part of the `docs-ohpc` package into `/opt/ohpc/pub/doc/recipes/vanilla/recipe.sh`. After enabling the OpenHPC repository and reviewing the guide for additional information on the intent of the commands, the general starting approach for using this template is as follows:

1. Install the `docs-ohpc` package

```
dnf -y install docs-ohpc
```

2. Copy the provided template input file to use as a starting point to define local site settings:

```
cp /opt/ohpc/pub/doc/recipes/rocky10/input.local input.local
```

3. Update `input.local` with desired settings
4. Copy the template installation script which contains command-line instructions culled from this guide.

```
cp -p /opt/ohpc/pub/doc/recipes/rocky10/aarch64/confluent/slurm/recipe.sh .
```

5. Review and edit `recipe.sh` to suite.
6. Use environment variable to define local input file and execute `recipe.sh` to perform a local installation.

```
export OHPC_INPUT_LOCAL=./input.local
./recipe.sh
```

# B Upgrading OpenHPC Packages

As newer OpenHPC releases are made available, users are encouraged to upgrade their locally installed packages against the latest repository versions to obtain access to bug fixes and newer component versions. This can be accomplished with the underlying package manager as OpenHPC packaging maintains versioning state across releases. Also, package builds available from the OpenHPC repositories have "`-ohpc`" appended to their names so that wild cards can be used as a simple way to obtain updates. The following general procedure highlights a method for upgrading existing installations. When upgrading from a minor release older than v4, you will first need to update your local OpenHPC repository configuration to point against the v4 release (or update your locally hosted mirror). Refer to an earlier section for more details on enabling the latest repository. In contrast, when upgrading between micro releases on the same branch (e.g. from v4 to 4.2), there is no need to adjust local package manager configurations when using the public repository as rolling updates are pre-configured.

1. (Optional) Ensure repo metadata is current (on head node and compute nodes). Package managers will naturally do this on their own over time, but if you are wanting to access updates immediately after a new release, the following can be used to sync to the latest.

```
dnf clean expire-cache
nodeshell compute dnf clean expire-cache
```

2. Upgrade head node

```
dnf -y upgrade "*-ohpc"

# Any new Base OS provided dependencies can be installed by
# updating the ohpc-base metapackage
dnf -y upgrade "ohpc-base"
```

3. Upgrade packages on compute nodes

```
nodeshell compute dnf -y upgrade "*-ohpc"

# Any new compute-node Base OS provided dependencies can be installed by
# updating the ohpc-base-compute metapackage
nodeshell compute dnf -y upgrade "ohpc-base-compute"
```

Note that to update running services such as a resource manager, a service restart is required on the compute nodes.

# C Integration Test Suite

This appendix details the installation and basic use of the integration test suite used to support OpenHPC releases. This suite is not intended to replace the validation performed by component development teams, but is instead, devised to confirm component builds are functional and interoperable within the modular OpenHPC environment. The test suite is generally organized by components and the OpenHPC CI workflow relies on running the full suite using Jenkins to test multiple OS configurations and installation recipes. To facilitate customization and running of the test suite locally, we provide these tests in a standalone RPM.

```
dnf -y install test-suite-ohpc
```

The RPM installation creates a user named `ohpc-test` to house the test suite and provide an isolated environment for execution. Configuration of the test suite is done using standard GNU autotools semantics and the BATS shell-testing framework is used to execute and log a number of individual unit tests. Some tests require privileged execution, so a different combination of tests will be enabled depending on which user executes the top-level `configure` script. Non-privileged tests requiring execution on one or more compute nodes are submitted as jobs through the SLURM resource manager. The tests are further divided into "short" and "long" run categories. The short run configuration is a subset of approximately 180 tests to demonstrate basic functionality of key components (e.g. MPI stacks) and should complete in 10-20 minutes. The long run (around 1000 tests) is comprehensive and can take an hour or more to complete.

Most components can be tested individually, but a default configuration is setup to enable collective testing. To test an isolated component, use the `configure` option to disable all tests, then re-enable the desired test to run. The `--help` option to `configure` will display all possible tests. By default, the test suite will endeavor to run tests for multiple MPI stacks where applicable. To restrict tests to only a subset of MPI families, use the `--with-mpi-families` option (e.g. `--with-mpi-families="openmpi4"`). Example output is shown below (some output is omitted for the sake of brevity).

```
su - ohpc-test
[test@sms ~]$ cd tests
[test@sms ~]$ ./configure --disable-all --enable-fftw
checking for a BSD-compatible install... /bin/install -c
checking whether build environment is sane... yes

----------------------------------- SUMMARY -----------------------------------

Package version.............. : test-suite-2.0.0

Build user................... : ohpc-test
Build host................... : sms001
Configure date............... : 2020-10-05 08:22
Build architecture........... : aarch64
Compiler Families............ : gnu9
MPI Families................. : mpich openmpi4
Python Families.............. : python3
Resource manager ............ : SLURM
Test suite configuration..... : short

Libraries:
    Adios ................... : disabled
    Boost ................... : disabled
    Boost MPI................ : disabled
    FFTW..................... : enabled
    GSL...................... : disabled
    HDF5..................... : disabled
    HYPRE.................... : disabled
```

Many OpenHPC components exist in multiple flavors to support multiple compiler and MPI runtime permutations, and the test suite takes this in to account by iterating through these combinations by default. If `make check` is executed from the top-level test directory, all configured compiler and MPI permutations of a library will be exercised. The following highlights the execution of the FFTW related tests that were enabled in the previous step.

```
[test@sms ~]$ make check
make --no-print-directory check-TESTS
PASS: libs/fftw/ohpc-tests/test_mpi_families
============================================================================
Testsuite summary for test-suite 2.0.0
============================================================================
# TOTAL: 1
# PASS:  1
# SKIP:  0
# XFAIL: 0
# FAIL:  0
# XPASS: 0
# ERROR: 0
============================================================================
[test@sms ~]$ cat libs/fftw/tests/family-gnu*/rm_execution.log
1..3
ok 1 [libs/FFTW] Serial C binary runs under resource manager (SLURM/gnu9/mpich)
ok 2 [libs/FFTW] MPI C binary runs under resource manager (SLURM/gnu9/mpich)
ok 3 [libs/FFTW] Serial Fortran binary runs under resource manager (SLURM/gnu9/mpich)
PASS rm_execution (exit status: 0)
1..3
ok 1 [libs/FFTW] Serial C binary runs under resource manager (SLURM/gnu9/openmpi4)
ok 2 [libs/FFTW] MPI C binary runs under resource manager (SLURM/gnu9/openmpi4)
ok 3 [libs/FFTW] Serial Fortran binary runs under resource manager (SLURM/gnu9/...
PASS rm_execution (exit status: 0)
```

# D Customization

## D.1 Adding local environment modules to OpenHPC hierarchy

Administrators may wish to add locally built software packages to the OpenHPC module hierarchy. This can be accomplished by creating module files in the appropriate locations under `/opt/ohpc/pub/moduledeps` or `/opt/ohpc/pub/modulefiles`. Two sample module files are included in the `examples-ohpc` package—one representing an application with no compiler or MPI runtime dependencies, and one dependent on OpenMPI and the GNU toolchain. Simply copy these files to the prescribed locations, and the `module` command should pick them up automatically. The example output below is from Lmod; Environment Modules lists the same modules in its own format.

```
# Create a simple example module
mkdir /opt/ohpc/pub/modulefiles/example1
cp /opt/ohpc/pub/examples/example.modulefile \
    /opt/ohpc/pub/modulefiles/example1/1.0

# Create an example module with a dependency
mkdir /opt/ohpc/pub/moduledeps/gnu7-openmpi3/example2
cp /opt/ohpc/pub/examples/example-mpi-dependent.modulefile \
    /opt/ohpc/pub/moduledeps/gnu7-openmpi3/example2/1.0

# Show modules
module avail
```

Example Output

```
---------------------- /opt/ohpc/pub/moduledeps/gnu7-openmpi3 -----------------------
   adios/1.12.0    imb/2018.0          netcdf-fortran/4.4.4    ptscotch/6.0.4
   boost/1.65.1    mpi4py/2.0.0        netcdf/4.4.1.1          scalapack/2.0.2
   example2/1.0    mpiP/3.4.1          petsc/3.7.6             scalasca/2.3.1
   fftw/3.3.6      mumps/5.1.1         phdf5/1.10.1            scipy/0.19.1
   hypre/2.11.2    netcdf-cxx/4.3.0    pnetcdf/1.8.1           scorep/3.1

--------------------------- /opt/ohpc/pub/moduledeps/gnu7 ---------------------------
   R/3.4.2        metis/5.1.0     ocr/1.0.1              pdtoolkit/3.24
   gsl/2.4        mpich/3.2       openblas/0.2.20        plasma/2.8.0
   hdf5/1.10.1    numpy/1.13.1    openmpi3/3.0.0  (L)    scotch/6.0.4

-------------------------- /opt/ohpc/admin/modulefiles --------------------------
   spack/0.10.0

-------------------------- /opt/ohpc/pub/modulefiles --------------------------
   EasyBuild/3.4.1         cmake/3.9.2         hwloc/1.11.8        pmix/1.2.3
   autotools        (L)    example1/1.0 (L)    llvm5/5.0.0         prun/1.2        (L)
   clustershell/1.8        gnu7/7.2.0   (L)    ohpc         (L)    singularity/2.4

  Where:
   L:  Module is loaded

Use "module spider" to find all possible modules.
Use "module keyword key1 key2 ..." to search for all possible modules matching any of
the "keys".
```

## D.2 Rebuilding Packages from Source

OpenHPC packages can be rebuilt from source using the source RPMs available from the OpenHPC repository. This allows administrators to customize package builds for their specific needs. One way to accomplish this is to install the appropriate source RPM, modify the spec file as needed, and rebuild to obtain an updated binary RPM. OpenHPC spec files contain macros to facilitate local customizations of compiler, compilation flags and MPI family. A brief example using the FFTW library is highlighted below. Note that the source RPMs can be downloaded from the community repository server at http://repos.openhpc.community via a web browser or directly via dnf as highlighted below. In this example we make an explicit change to FFTW's configuration, as well as modifying the CFLAGS environment variable. The package is also tagged with an additional delimiter to allow easy co-installation and use.

```
# Install rpm-build package and dnf tools from base OS distro
sudo dnf -y install rpm-build dnf-plugins-core

# Install FFTW's build dependencies
sudo dnf builddep fftw-gnu16-openmpi5-ohpc

# Download SRPM from OpenHPC repository and install locally
dnf download --source fftw-gnu16-openmpi5-ohpc
rpm -i ./fftw-gnu16-openmpi5-ohpc-*.rpm

# Modify spec file as desired
cd ~/rpmbuild/SPECS
sed -i "s/enable-static=no/enable-static=yes/" fftw.spec

# Increment RPM release so the package manager will see an update
sed -i "s/Release:   400.ohpc.3.1/Release:   400.ohpc.3.2/" fftw.spec

# Rebuild binary RPM. Note that additional directives can be specified to modify build
rpmbuild -bb --define "OHPC_CFLAGS '-O3 -mtune=native'" \
        --define "OHPC_CUSTOM_DELIM static" fftw.spec

# Install the new package
sudo dnf -y install \
        ../RPMS/$(uname -m)/fftw-gnu16-openmpi5-static-ohpc-*.$(uname -m).rpm
```

The new module file now appears along side the default.

```
$ module -t spider fftw
fftw/3.3.10-static
fftw/3.3.10
```

# E Package Manifest

This appendix provides a summary of available meta-package groupings and all of the individual RPM packages that are available as part of this OpenHPC release. The meta-packages provide a mechanism to group related collections of RPMs by functionality and provide a convenience mechanism for installation. A list of the available meta-packages and a brief description is presented in the table below.

## E.1 Available OpenHPC Meta-packages

| Group Name | Description |
|---|---|
| ohpc-arm1-io-libs | Collection of IO library builds for use with the Arm Compiler for Linux toolchain. |
| ohpc-arm1-mpich-parallel-libs | Collection of parallel library builds for use with the Arm Compiler for Linux and the MPICH runtime. |
| ohpc-arm1-openmpi5-parallel-libs | Collection of parallel library builds for use with the Arm Compiler for Linux and the openmpi5 runtime. |
| ohpc-arm1-perf-tools | Collection of performance tool builds for use with the Arm Compiler for Linux toolchain. |
| ohpc-arm1-python3-libs | Collection of python3 related library builds for use with the Arm Compiler for Linux toolchain. |
| ohpc-arm1-serial-libs | Collection of serial library builds for use with the Arm Compiler for Linux toolchain. |
| ohpc-autotools | Collection of GNU autotools packages. |
| ohpc-base | Collection of base packages. |
| ohpc-base-compute | Collection of compute node base packages. |
| ohpc-flux-client | Collection of client packages for Flux. |
| ohpc-flux-server | Collection of server packages for Flux. |
| ohpc-gnu15-io-libs | Collection of IO library builds for use with GNU compiler toolchain. |
| ohpc-gnu15-mpich-io-libs | Collection of IO library builds for use with GNU compiler toolchain and the MPICH runtime. |
| ohpc-gnu15-mpich-parallel-libs | Collection of parallel library builds for use with GNU compiler toolchain and the MPICH runtime. |
| ohpc-gnu15-mpich-perf-tools | Collection of performance tool builds for use with GNU compiler toolchain and the MPICH runtime. |
| ohpc-gnu15-openmpi5-io-libs | Collection of IO library builds for use with GNU compiler toolchain and the OpenMPI runtime. |
| ohpc-gnu15-openmpi5-parallel-libs | Collection of parallel library builds for use with GNU compiler toolchain and the OpenMPI runtime. |
| ohpc-gnu15-openmpi5-perf-tools | Collection of performance tool builds for use with GNU compiler toolchain and the OpenMPI runtime. |
| ohpc-gnu15-parallel-libs | Collection of parallel library builds for use with GNU compiler toolchain. |
| ohpc-gnu15-perf-tools | Collection of performance tool builds for use with GNU compiler toolchain. |
| ohpc-gnu15-python-libs | Collection of python related library builds for use with GNU compiler toolchain. |

| Group Name | Description |
|---|---|
| ohpc-gnu15-python3-libs | Collection of python3 related library builds for use with GNU compiler toolchain. |
| ohpc-gnu15-runtimes | Collection of runtimes for use with GNU compiler toolchain. |
| ohpc-gnu15-serial-libs | Collection of serial library builds for use with GNU compiler toolchain. |
| ohpc-gnu16-io-libs | Collection of IO library builds for use with GNU compiler toolchain. |
| ohpc-gnu16-mpich-io-libs | Collection of IO library builds for use with GNU compiler toolchain and the MPICH runtime. |
| ohpc-gnu16-mpich-parallel-libs | Collection of parallel library builds for use with GNU compiler toolchain and the MPICH runtime. |
| ohpc-gnu16-mpich-perf-tools | Collection of performance tool builds for use with GNU compiler toolchain and the MPICH runtime. |
| ohpc-gnu16-openmpi5-io-libs | Collection of IO library builds for use with GNU compiler toolchain and the OpenMPI runtime. |
| ohpc-gnu16-openmpi5-parallel-libs | Collection of parallel library builds for use with GNU compiler toolchain and the OpenMPI runtime. |
| ohpc-gnu16-openmpi5-perf-tools | Collection of performance tool builds for use with GNU compiler toolchain and the OpenMPI runtime. |
| ohpc-gnu16-parallel-libs | Collection of parallel library builds for use with GNU compiler toolchain. |
| ohpc-gnu16-perf-tools | Collection of performance tool builds for use with GNU compiler toolchain. |
| ohpc-gnu16-python-libs | Collection of python related library builds for use with GNU compiler toolchain. |
| ohpc-gnu16-python3-libs | Collection of python3 related library builds for use with GNU compiler toolchain. |
| ohpc-gnu16-runtimes | Collection of runtimes for use with GNU compiler toolchain. |
| ohpc-gnu16-serial-libs | Collection of serial library builds for use with GNU compiler toolchain. |
| ohpc-slurm-client | Collection of client packages for SLURM. |
| ohpc-slurm-server | Collection of server packages for SLURM. |
| ohpc-warewulf | Collection of base packages for Warewulf provisioning. |

## E.2 RPM Packages

What follows next in this Appendix is a series of tables that summarize the underlying RPM packages available in this OpenHPC release. These packages are organized by groupings based on their general functionality and each table provides information for the specific RPM name, version, brief summary, and the web URL where additional information can be obtained for the component. Note that many of the 3rd party community libraries that are pre-packaged with OpenHPC are built using multiple compiler and MPI families. In these cases, the RPM package name includes delimiters identifying the development environment for which each package build is targeted. Additional information on the OpenHPC package naming scheme is presented in Section 3rd Party Packages. The relevant package groupings and associated references are as follows:

- Administrative Tools

- Resource Management
- Compiler Families
- MPI Families / Communication Libraries
- Development Tools
- Performance Analysis Tools
- IO Libraries
- Distro Packages
- Runtimes
- Serial/Threaded Libraries
- Parallel Libraries

### E.2.1 Administrative Tools

| RPM Package Name | Version | Info/URL |
|---|---|---|
| conman | 0.3.1 | ConMan: The Console Manager. http://dun.github.io/conman |
| docs | 4.0.0 | OpenHPC documentation. https://github.com/openhpc/ohpc |
| docs | 4.2.0 | OpenHPC documentation. https://github.com/openhpc/ohpc |
| environment-modules | 5.7.0 | Provides dynamic modification of a user's environment. https://envmodules.io |
| examples | 2.0 | Example source code and templates for use within OpenHPC environment. https://github.com/openhpc/ohpc |
| genders | 1.32 | Static cluster configuration database. https://github.com/chaos/genders |
| hpc-workspace | 1.6.3 | Temporary workspace management. https://github.com/holgerBerger/hpc-workspace |
| lmod-defaults | 2.0 | OpenHPC default login environments. https://github.com/openhpc/ohpc |
| lmod | 9.4.5 | Lua based Modules (lmod). https://github.com/TACC/Lmod |
| losf | 0.56.0 | A Linux operating system framework for managing HPC clusters. https://github.com/hpcsi/losf |
| modules-defaults | 2.1 | OpenHPC default login environments. https://github.com/openhpc/ohpc |
| nhc | 1.4.3 | LBNL Node Health Check. https://github.com/mej/nhc |
| ohpc-release | 4 | OpenHPC release files. https://github.com/openhpc/ohpc |
| pdsh | 2.36 | Parallel remote shell program. https://github.com/chaos/pdsh |
| prun | 3 | Convenience utility for parallel job launch. https://github.com/openhpc/ohpc |

| RPM Package Name | Version | Info/URL |
|---|---|---|
| test-suite | 4.2.0 | Integration test suite for OpenHPC. https://github.com/openhpc/ohpc |

### E.2.2 Resource Management

| RPM Package Name | Version | Info/URL |
|---|---|---|
| flux-core | 0.89.0 | Core components of the Flux resource manager framework. https://github.com/flux-framework/flux-core |
| flux | 0.7.1 | PMIx support for the Flux resource manager. https://github.com/flux-framework/flux-pmix |
| flux-sched | 0.55.0 | Fluxion graph-based scheduler for the Flux resource manager. https://github.com/flux-framework/flux-sched |
| flux-security | 0.15.0 | Independent security component for the Flux resource manager. https://github.com/flux-framework/flux-security |
| magpie | 3.2 | Scripts for running Big Data software in HPC environments. https://github.com/LLNL/magpie |
| openpbs-client | 23.06.06 | OpenPBS for a client host. http://www.openpbs.org |
| openpbs-execution | 23.06.06 | OpenPBS for an execution host. http://www.openpbs.org |
| openpbs-server | 23.06.06 | OpenPBS for a server host. http://www.openpbs.org |
| pmix | 4.2.9 | An extended/exascale implementation of PMI. https://pmix.org |
| slurm-contribs | 26.05.5 | Perl tool to print Slurm job state information. https://slurm.schedmd.com |
| slurm-devel | 26.05.5 | Development package for Slurm. https://slurm.schedmd.com |
| slurm-example-configs | 26.05.5 | Example config files for Slurm. https://slurm.schedmd.com |
| slurm-libpmi | 26.05.5 | Slurm's implementation of the pmi libraries. https://slurm.schedmd.com |
| slurm | 26.05.5 | Slurm Workload Manager. https://slurm.schedmd.com |
| slurm-openlava | 26.05.5 | openlava/LSF wrappers for transition from OpenLava/LSF to Slurm. https://slurm.schedmd.com |
| slurm-pam_slurm | 26.05.5 | PAM module for restricting access to compute nodes via Slurm. https://slurm.schedmd.com |
| slurm-perlapi | 26.05.5 | Perl API to Slurm. https://slurm.schedmd.com |
| slurm-sackd | 26.05.5 | Slurm authentication daemon. https://slurm.schedmd.com |
| slurm-slurmctld | 26.05.5 | Slurm controller daemon. https://slurm.schedmd.com |
| slurm-slurmd | 26.05.5 | Slurm compute node daemon. https://slurm.schedmd.com |
| slurm-slurmdbd | 26.05.5 | Slurm database daemon. https://slurm.schedmd.com |
| slurm-sview | 26.05.5 | Graphical user interface to view and modify Slurm state. https://slurm.schedmd.com |
| slurm-torque | 26.05.5 | Torque/PBS wrappers for transition from Torque/PBS to Slurm. https://slurm.schedmd.com |

### E.2.3 Compiler Families

| RPM Package Name | Version | Info/URL |
|---|---|---|
| gnu15-compilers | 15.2.0 | The GNU C Compiler and Support Files. http://gcc.gnu.org |
| gnu16-compilers | 16.2.0 | The GNU C Compiler and Support Files. http://gcc.gnu.org |

### E.2.4 MPI Families / Communication Libraries

| RPM Package Name | Version | Info/URL |
|---|---|---|
| mpich | 5.0.1 | MPICH MPI implementation. http://www.mpich.org |
| openmpi5 | 5.0.10 | A powerful implementation of MPI/SHMEM. http://www.open-mpi.org |
| ucx | 1.22.0 | UCX is a communication library implementing high-performance messaging. http://www.openucx.org |

### E.2.5 Development Tools

| RPM Package Name | Version | Info/URL |
|---|---|---|
| EasyBuild | 5.4.1 | Software build and installation framework. https://easybuild.io |
| autoconf | 2.71 | A GNU tool for automatically configuring source code. http://www.gnu.org/software/autoconf |
| automake | 1.16.5 | A GNU tool for automatically creating Makefiles. http://www.gnu.org/software/automake |
| cmake | 4.4.4 | CMake is an open-source, cross-platform family of tools designed to build, test and package software. https://cmake.org |
| cuda-devel | 25.9 | OpenHPC compatibility package for cuda. https://github.com/openhpc/ohpc |
| cuda-repo | 25.9 | Cuda toolkit online repository. https://github.com/openhpc/ohpc |
| hwloc | 2.15.0 | Portable Hardware Locality. http://www.open-mpi.org/projects/hwloc |
| libtool | 2.4.6 | The GNU Portable Library Tool. http://www.gnu.org/software/libtool |
| python3-mpi4py | 4.1.1 | Python bindings for the Message Passing Interface (MPI) standard. https://github.com/mpi4py/mpi4py |
| python3-numpy | 2.4.4 | NumPy array processing for numbers, strings, records and objects. https://github.com/numpy/numpy |
| spack | 1.2.2 | HPC software package management. https://github.com/spack/spack |
| valgrind | 3.27.1 | Valgrind Memory Debugger. http://www.valgrind.org |

### E.2.6 Performance Analysis Tools

| RPM Package Name | Version | Info/URL |
|---|---|---|
| dimemas | 5.5.0 | Dimemas tool. https://tools.bsc.es |
| extrae | 5.0.4 | Extrae tool. https://tools.bsc.es |
| imb | 2021.11 | Intel MPI Benchmarks (IMB). https://software.intel.com/en-us/articles/intel-mpi-benchmarks |
| likwid | 5.5.1 | Performance tools for the Linux console. https://github.com/RRZE-HPC/likwid |
| omb | 7.5.2 | OSU Micro-benchmarks. https://mvapich.cse.ohio-state.edu/benchmarks |
| papi | 7.2.0 | Performance Application Programming Interface. http://icl.cs.utk.edu/papi |
| paraver | 4.12.0 | Paraver. https://tools.bsc.es |
| pdtoolkit | 3.25.1 | PDT is a framework for analyzing source code. http://www.cs.uoregon.edu/Research/pdt |
| scalasca | 2.6.2 | Toolset for performance analysis of large-scale parallel applications. http://www.scalasca.org |
| scorep | 9.4 | Scalable Performance Measurement Infrastructure for Parallel Codes. http://www.vi-hps.org/projects/score-p |
| tau | 2.35.1 | Tuning and Analysis Utilities Profiling Package. http://www.cs.uoregon.edu/research/tau/home.php |

### E.2.7 IO Libraries

| RPM Package Name | Version | Info/URL |
|---|---|---|
| adios2 | 2.12.0 | The Adaptable IO System v2 (ADIOS2). https://adios2.readthedocs.io/en/latest/index.html |
| cubew | 4.9.1 | CUBE Uniform Behavioral Encoding generic presentation writer component. http://www.scalasca.org/software/cube-4.x/download.html |
| hdf5 | 2.1.1 | A general purpose library and file format for storing scientific data. http://www.hdfgroup.org/HDF5 |
| netcdf-cxx | 4.3.1 | C++ Libraries for the Unidata network Common Data Form. http://www.unidata.ucar.edu/software/netcdf |
| netcdf-fortran | 4.6.2 | Fortran Libraries for the Unidata network Common Data Form. http://www.unidata.ucar.edu/software/netcdf |
| netcdf | 4.10.0 | C Libraries for the Unidata network Common Data Form. http://www.unidata.ucar.edu/software/netcdf |
| otf2 | 3.1.1 | Open Trace Format 2 library. http://score-p.org |
| phdf5 | 2.1.1 | A general purpose library and file format for storing scientific data (parallel version). http://www.hdfgroup.org/HDF5 |
| pnetcdf | 1.14.1 | A Parallel NetCDF library (PnetCDF). http://cucis.ece.northwestern.edu/projects/PnetCDF |

| RPM Package Name | Version | Info/URL |
|---|---|---|
| sionlib | 1.7.7 | Scalable I/O Library for Parallel Access to Task-Local Files. https://apps.fz-juelich.de/jsc/sionlib/docu/index.html |

#### E.2.8 Distro Packages

| RPM Package Name | Version | Info/URL |
|---|---|---|
| python3-Cython | 3.3.0 | The Cython compiler for writing C extensions for the Python language. http://www.cython.org |

#### E.2.9 Runtimes

| RPM Package Name | Version | Info/URL |
|---|---|---|
| charliecloud | 0.45.2 | Lightweight user-defined software stacks for high-performance computing. https://charliecloud.io |

#### E.2.10 Serial/Threaded Libraries

| RPM Package Name | Version | Info/URL |
|---|---|---|
| R | 4.5.3 | R is a language and environment for statistical computing and graphics (S-Plus like). http://www.r-project.org |
| cubelib | 4.9.1 | CUBE Uniform Behavioral Encoding generic presentation library component. http://www.scalasca.org/software/cube-4.x/download.html |
| gotcha | 1.0.8 | A library for wrapping function calls to shared libraries. https://github.com/llnl/gotcha |
| gsl | 2.8 | GNU Scientific Library (GSL). http://www.gnu.org/software/gsl |
| metis | 5.1.0 | Serial Graph Partitioning and Fill-reducing Matrix Ordering. http://glaros.dtc.umn.edu/gkhome/metis/metis/overview |
| opari2 | 2.0.9 | An OpenMP runtime performance measurement instrumenter. https://www.vi-hps.org/projects/score-p |
| openblas | 0.3.32 | An optimized BLAS library based on GotoBLAS2. http://www.openblas.net |
| plasma | 25.5.27 | Parallel Linear Algebra Software for Multicore Architectures. https://github.com/icl-utk-edu/plasma |
| scotch | 7.0.11 | Graph, mesh and hypergraph partitioning library. https://gitlab.inria.fr/scotch/scotch |
| superlu | 7.0.1 | A general purpose library for the direct solution of linear equations. http://crd.lbl.gov/~xiaoye/SuperLU |

### E.2.11 Parallel Libraries

| RPM Package Name | Version | Info/URL |
|---|---|---|
| boost | 1.90.0 | Free peer-reviewed portable C++ source libraries. http://www.boost.org |
| fftw | 3.3.10 | A Fast Fourier Transform library. http://www.fftw.org |
| hypre | 3.1.0 | Scalable algorithms for solving linear systems of equations. http://www.llnl.gov/casc/hypre |
| mfem | 4.9 | Lightweight, general, scalable C++ library for finite element methods. http://mfem.org |
| mumps | 5.8.2 | A MUltifrontal Massively Parallel Sparse direct Solver. https://mumps-solver.org |
| petsc | 3.25.0 | Portable Extensible Toolkit for Scientific Computation. http://www.mcs.anl.gov/petsc |
| ptscotch | 7.0.11 | Graph, mesh and hypergraph partitioning library using MPI. https://gitlab.inria.fr/scotch/scotch |
| scalapack | 2.2.3 | A subset of LAPACK routines redesigned for heterogeneous computing. https://netlib.org/scalapack |
| slepc | 3.25.0 | A library for solving large scale sparse eigenvalue problems. http://slepc.upv.es |
| superlu_dist | 9.2.1 | A general purpose library for the direct solution of linear equations. https://portal.nersc.gov/project/sparse/superlu |
| trilinos | 17.0.0 | A collection of libraries of numerical algorithms. https://trilinos.org |

# F Package Signatures

All of the RPMs provided via the OpenHPC repository are signed with a GPG signature. By default, the underlying package managers will verify these signatures during installation to ensure that packages have not been altered. The RPMs can also be manually verified and the public signing key fingerprint for the latest repository is shown below:

```
Fingerprint: 5E33 3CA3 A1BD BBC9 DF14 9D74 09AD FAE4 **D722A692**
```

The following command can be used to verify an RPM once it has been downloaded locally by confirming if the package is signed, and if so, indicating which key was used to sign it. The example below highlights usage for a local copy of the `docs-ohpc` package and illustrates how the **key ID** matches the fingerprint shown above.

```
rpm --checksig -v ohpc-release-4-1.el10.x86_64.rpm
ohpc-release-4-1.el10.x86_64.rpm:
    Header V3 RSA/SHA256 Signature, key ID d722a692: OK
    Header SHA256 digest: OK
    Header SHA1 digest: OK
    Payload SHA256 digest: OK
    V3 RSA/SHA256 Signature, key ID d722a692: OK
    MD5 digest: OK
```